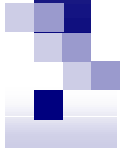


Search for satisfaction

Toby Walsh

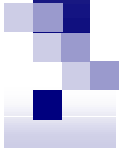
Cork Constraint Computation
Center

tw@4c.ucc.ie



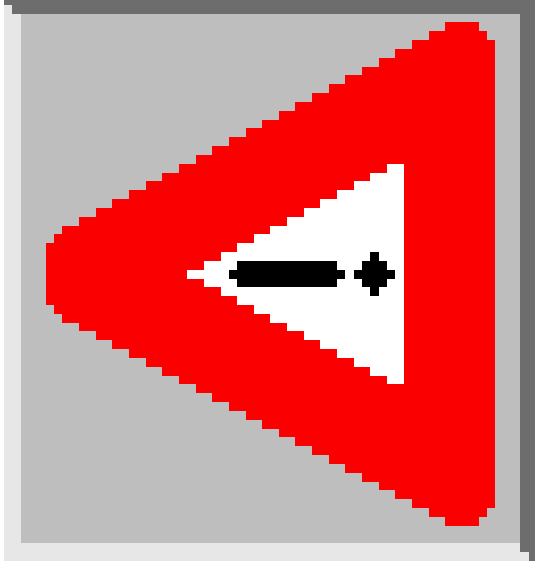
Cork Constraint Computation Center (4C)

- Gene Freuder (director)
 - □ **6M from SFI**
- Toby Walsh (PI)
 - □ **1.5M from SFI**
- ~20 staff
 - **Gene's 3C group from NH (Wallace, ...)**
 - **Existing Cork people (Bowen, O'Sullivan, ...)**
 - **Lots of new staff (Beck & Little from ILOG, ..., your name here)**
- Research themes
 - **Modelling**
 - eliminating the consultant
 - **Uncertainty**
 - **Robustness**
- Cork
 - **Ireland's 2nd city**
 - **Cultural capital**




Health warning

- To cover more ground, credit & references may not always be given
- Many active researchers in this area:
Achlioptas, Boros, Chaynes, Dunne, Eiter, Franco, Gent, Gomes, Hogg, ..., Walsh, ...,Zhang





Search for satisfaction

- Multi-media survey 
 - “hot” research area
- My next stop
 - 5th International Symposium on SAT (SAT-2002)
 - 1 panel, 3 invited speakers, 9 competing systems, 50 talks





Satisfaction

- Propositional satisfiability (SAT)
 - **does a truth assignment exist that satisfies a propositional formula?**
 - **NP-complete**

($x_1 \vee x_2$) & ($\neg x_2 \vee x_3 \vee \neg x_4$)

x_1 / True, x_2 / False, ...

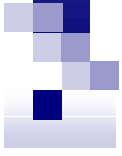


Satisfaction

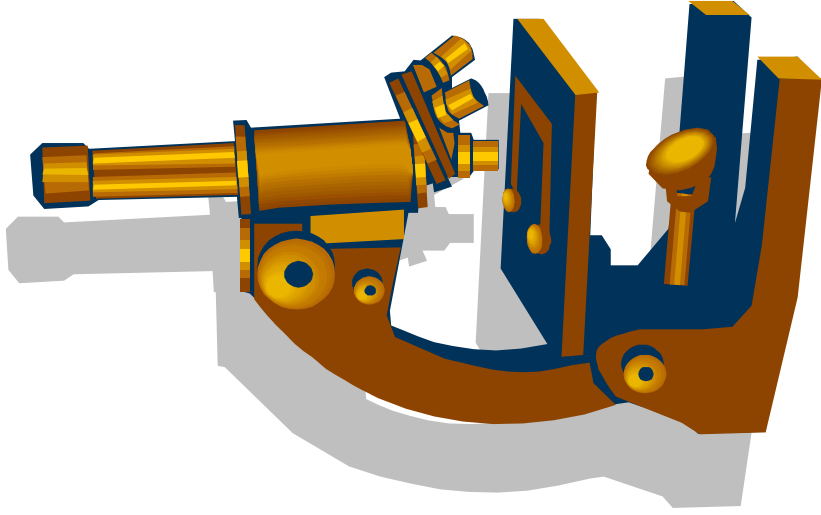
- Propositional satisfiability (SAT)
 - does a truth assignment exist that satisfies a propositional formula?
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($x_1 \vee x_2$) & ($\neg x_2 \vee x_3 \vee \neg x_4$)
 x_1 / True, x_2 / False, ...

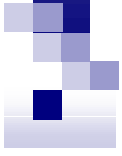
- 3-SAT
 - formulae in clausal form with 3 literals per clause
 - remains NP-complete



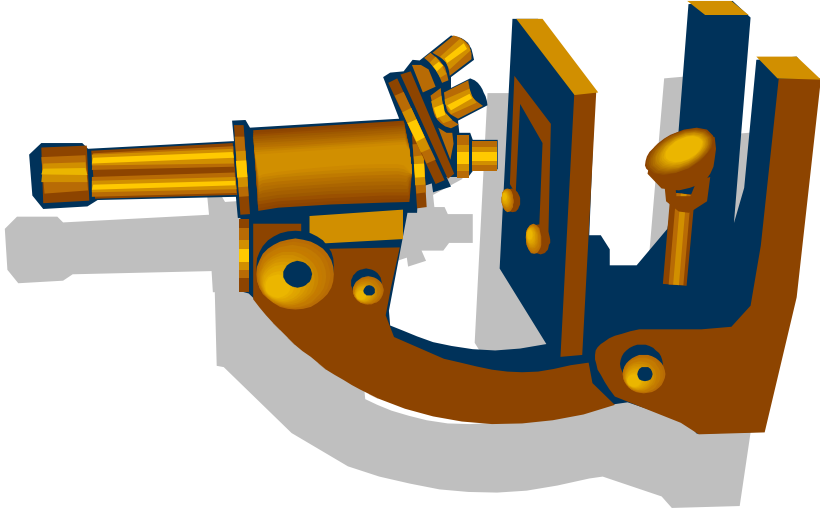
Why search for **satisfaction**?



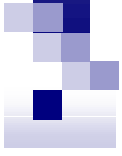
- Effective method to solve many problems
 - **Model checking**
 - **Diagnosis**
 - **Planning**
 - ...



Why search for **satisfaction**?

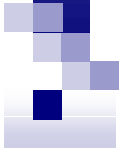


- Effective method to solve many problems
 - **Model checking**
 - **Diagnosis**
 - **Planning**
 - ...
- Simple domain in which to understand
 - **Problem hardness**
 - **NP-hard search**
 - ...



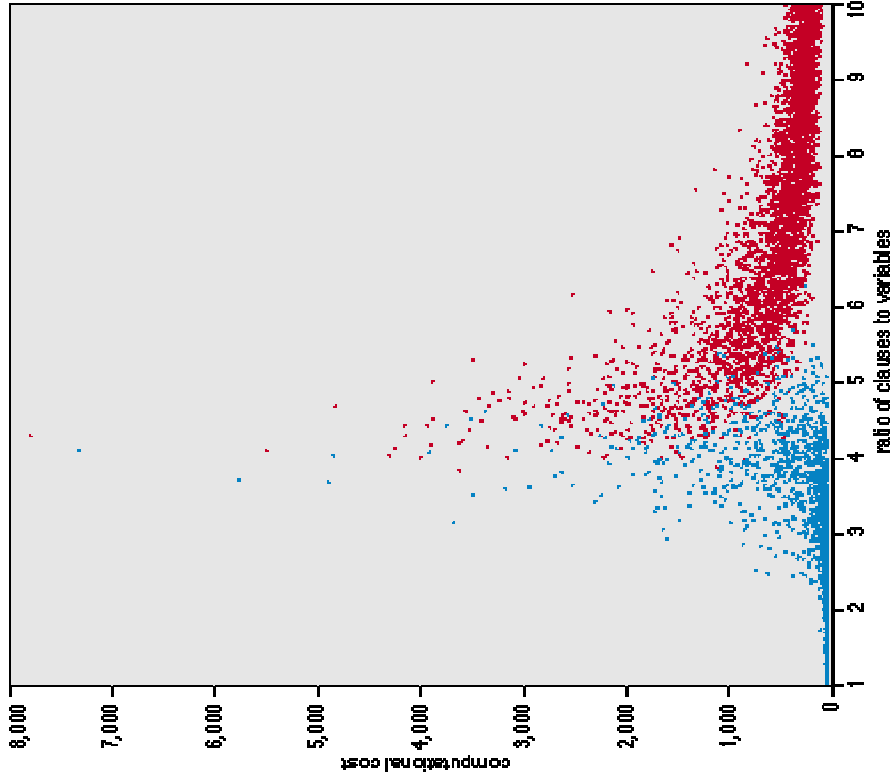
Outline

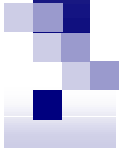
- SAT phase transition
 - **Why it might be important for you?**
- Problem structure
 - **Backbones**
- Real v random problems
 - **Small world graphs**
- Open problems
- Conclusions



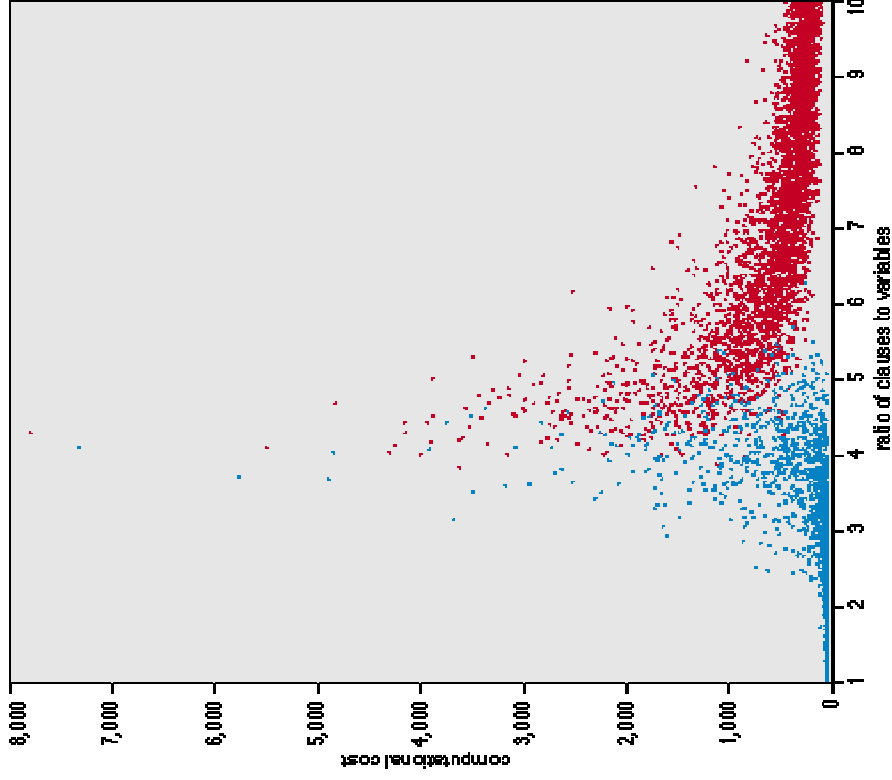
Random 3-SAT

- Random 3-SAT
 - sample uniformly from space of all possible 3-clauses
 - n variables, l clauses





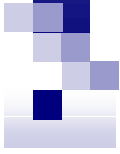
Random 3-SAT



- Random 3-SAT
 - sample uniformly from space of all possible 3-clauses
 - n variables, l clauses
- Which are the hard instances?
 - around $l/n = 4.3$

What happens with larger problems?

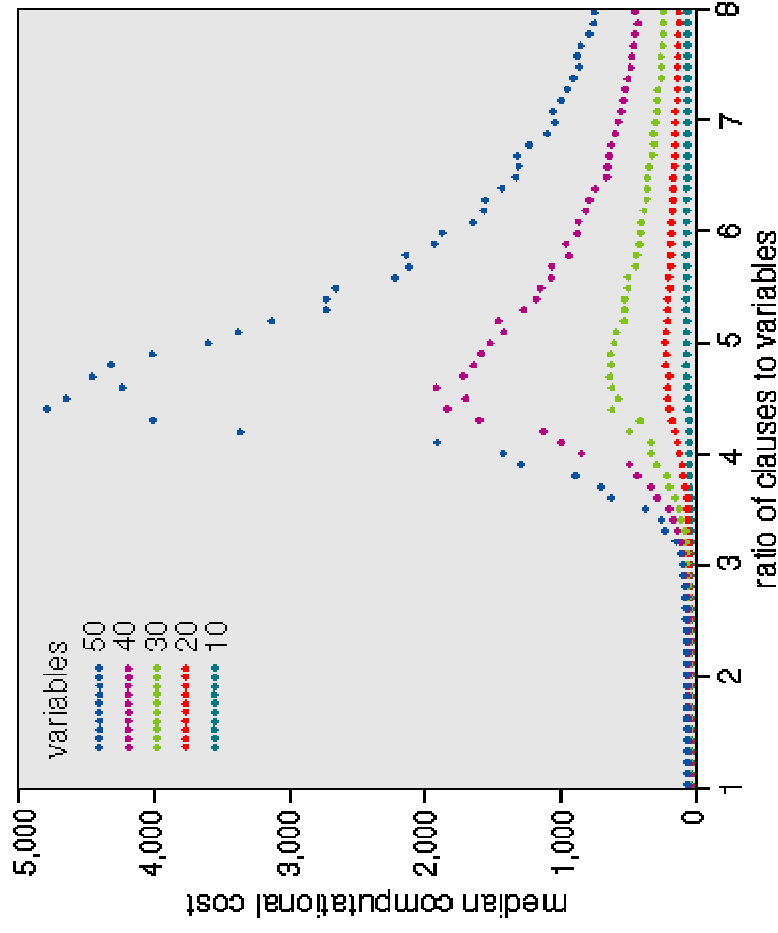
Why are some dots red and others blue?



Random 3-SAT

- Varying problem size, n
- Complexity peak appears to be largely invariant of algorithm
 - **backtracking algorithms** like **Davis-Putnam**
 - **local search procedures** like **GSAT**

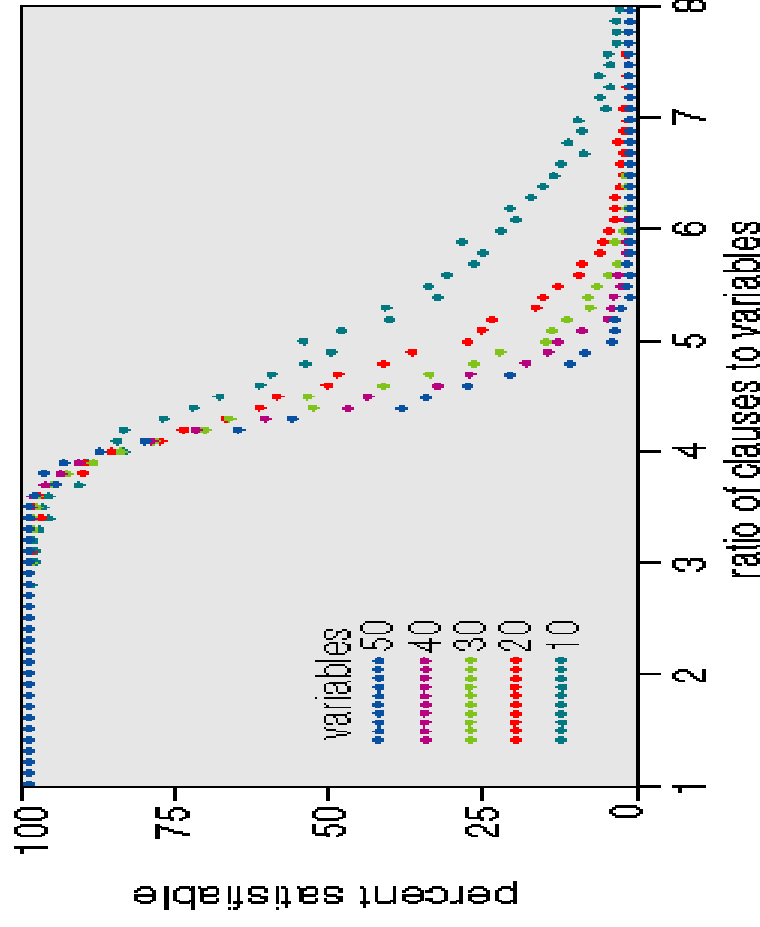
What's so special about 4.3?





Random 3-SAT

■ Complexity peak coincides with solubility transition

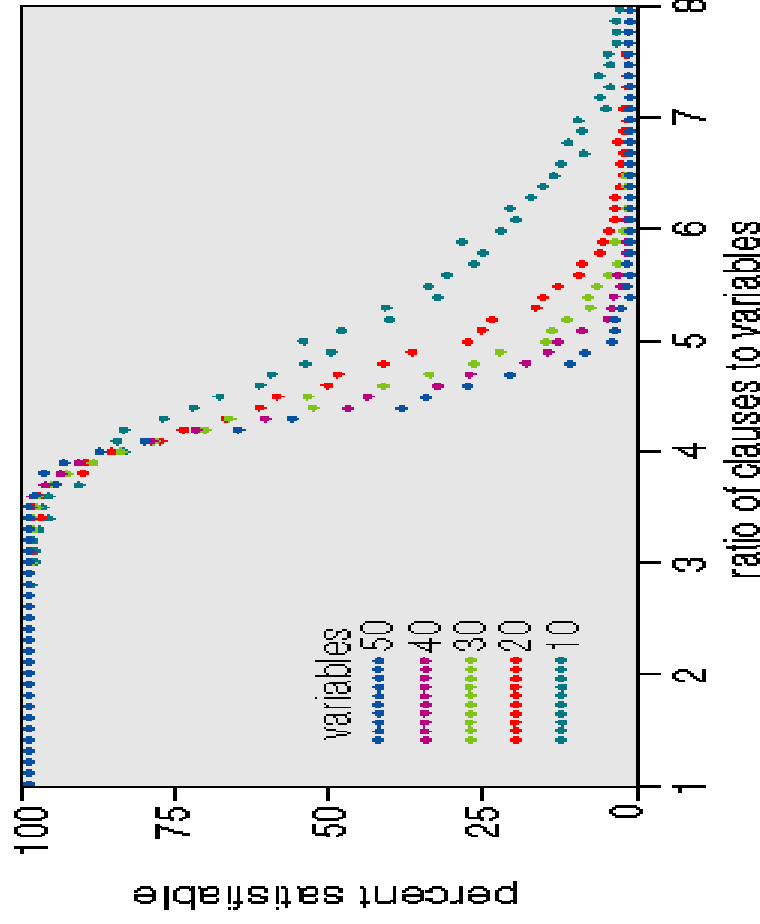


- $l/n < 4.3$ problems under-constrained and SAT
- $l/n > 4.3$ problems over-constrained and UNSAT

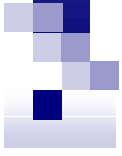


Random 3-SAT

■ Complexity peak coincides with solubility transition

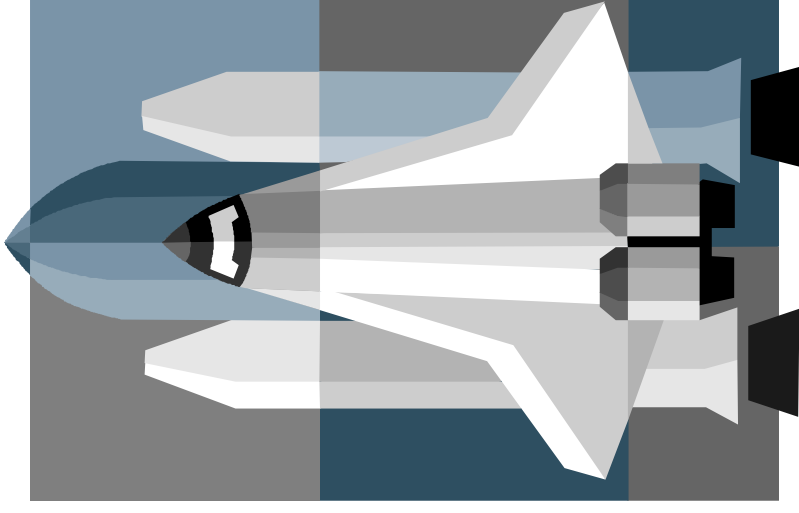


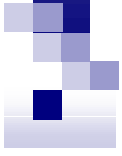
- $l/n < 4.3$ problems under-constrained and SAT
- $l/n > 4.3$ problems over-constrained and UNSAT
- $l/n = 4.3$, problems on “knife-edge” between SAT and UNSAT



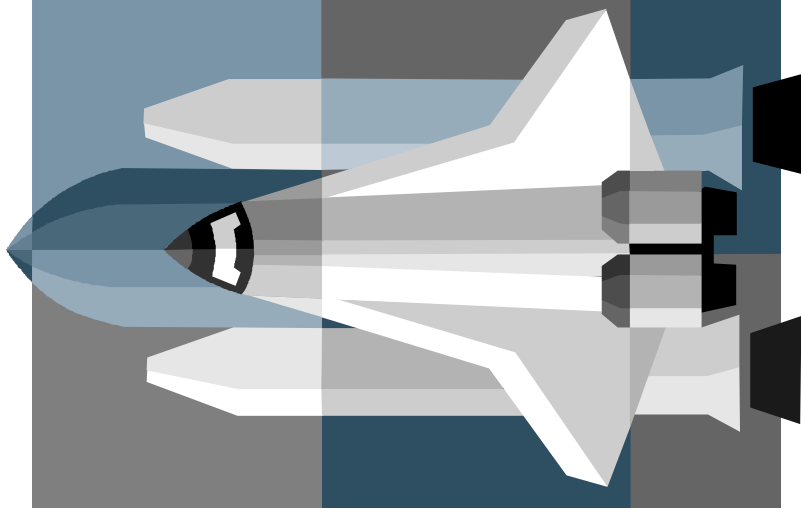
So, what's the relevance?

- Livingstone model-based diagnosis system
 - **Deep Space One**
- Tough operating constraints
 - **Autonomous**
 - **Real time**
 - **Limited computational resources**
- Compiled down to propositional theory ...

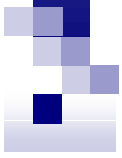




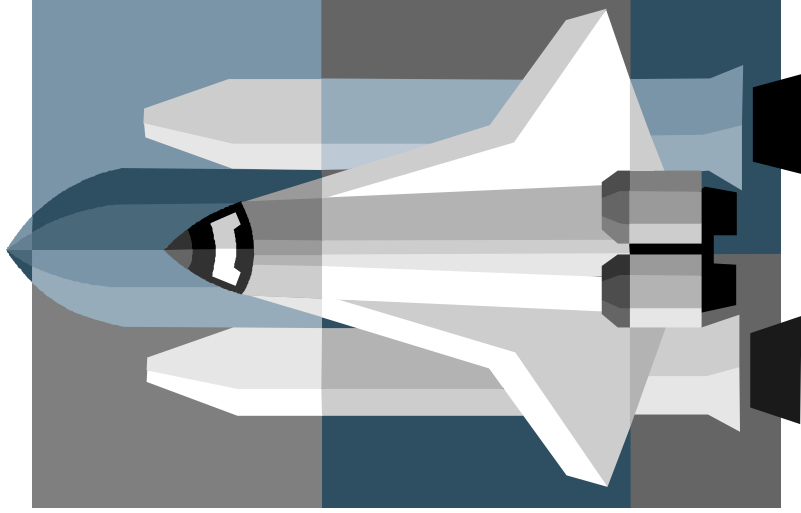
Deep Space One



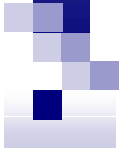
- Limited computational resources
- Deep Space One model has 2^{160} states



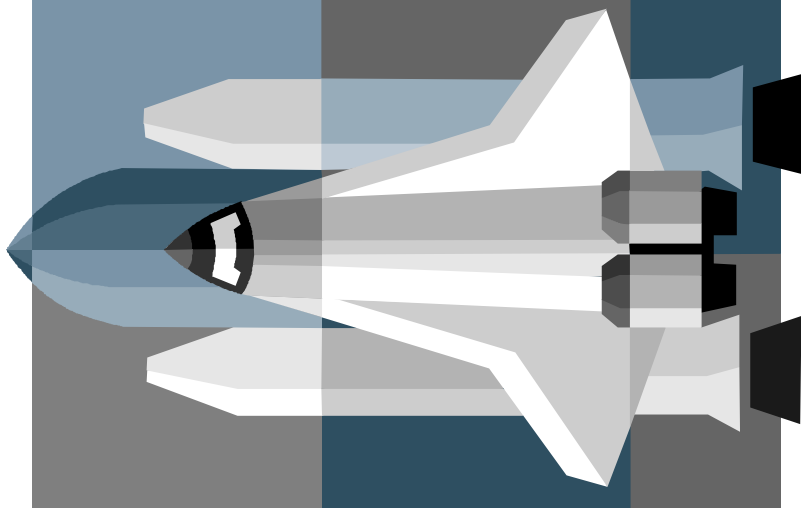
Deep Space One



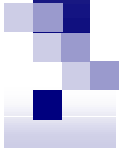
- Limited computational resources
- Deep Space One model has 2^{160} states
- Fortunately, far from phase boundary



Deep Space One



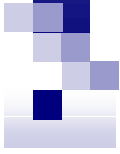
- Limited computational resources
- Deep Space One model has 2^{160} states
- Fortunately, far from phase boundary
- Not so surprising
 - **Very over-engineered**



So what's the relevance?

- Model checking
 - Does an implementation satisfy a specification?
 - PSpace in general
- So how can SAT help?
 - It's only **NP-complete!**

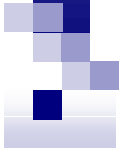




So what's the relevance?

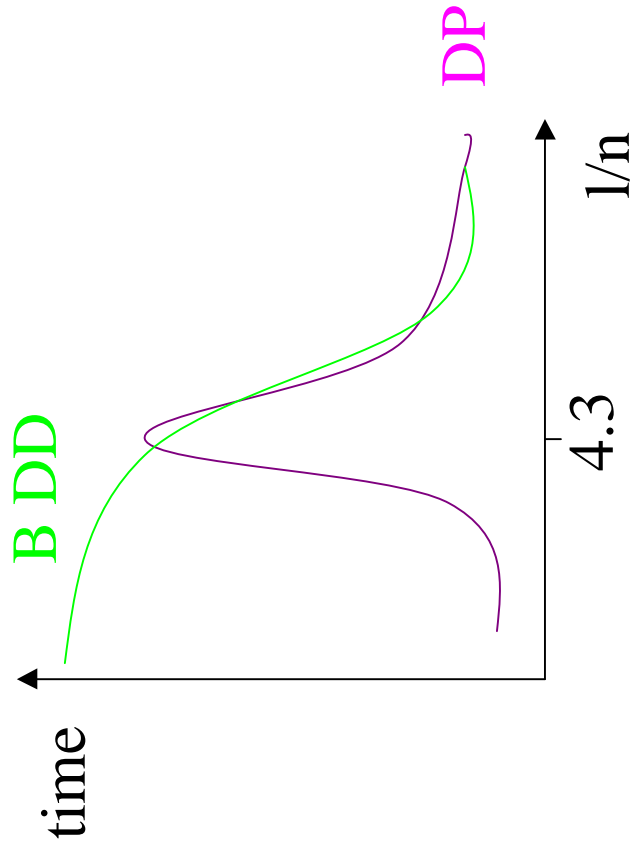
- Model checking
 - Does an implementation satisfy a specification?
 - PSpace in general
- So how can SAT help?
 - Bounded model checking
 - Bound = path length in state transition diagram

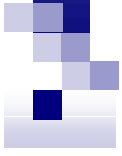




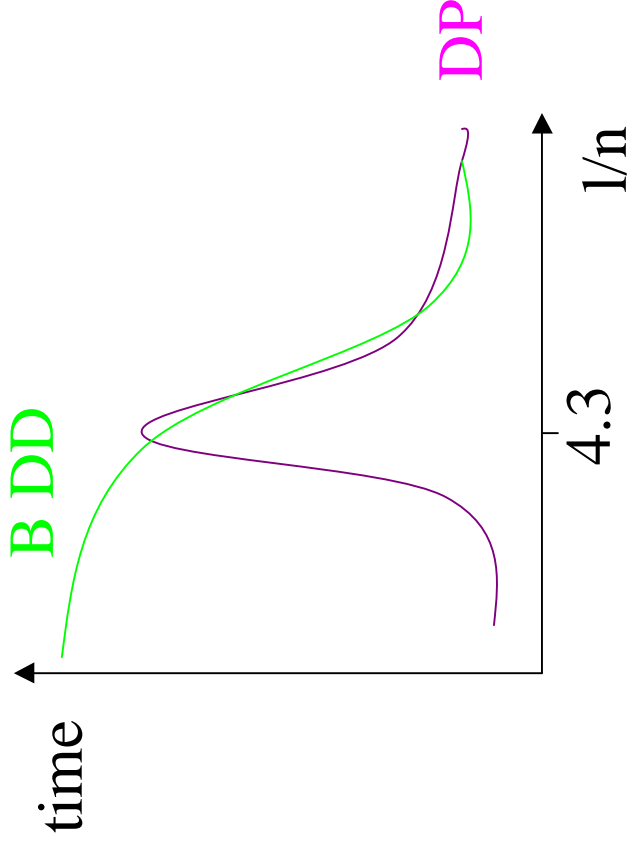
Model checking

- SAT solvers (e.g. Davis Putnam) very effective at finding bugs
 - **BDDs good at proving correctness**





Model checking



- SAT solvers (e.g. Davis Putnam) very effective at finding bugs
 - **BDDs good at proving correctness**
- Surprised it took so long to see benefits of SAT solvers
 - **DP is $O(n)$ space, $O(2^n)$ time**
 - **BDDs are $O(2^n)$ space and time**
 - **Memory isn't that cheap**



“But phase transitions don’t occur in X?”

- X = some NP-complete problem
- X = real problems
- X = some other complexity class

Little evidence yet to support any of these claims!



“But it doesn’t occur in X?”

- X = some NP-complete problem
- Phase transition behaviour seen in:
 - **TSP problem (decision not optimization)**
 - **Hamiltonian circuits (but NOT a complexity peak)**
 - **number partitioning**
 - **graph colouring**
 - **independent set**
 - ...

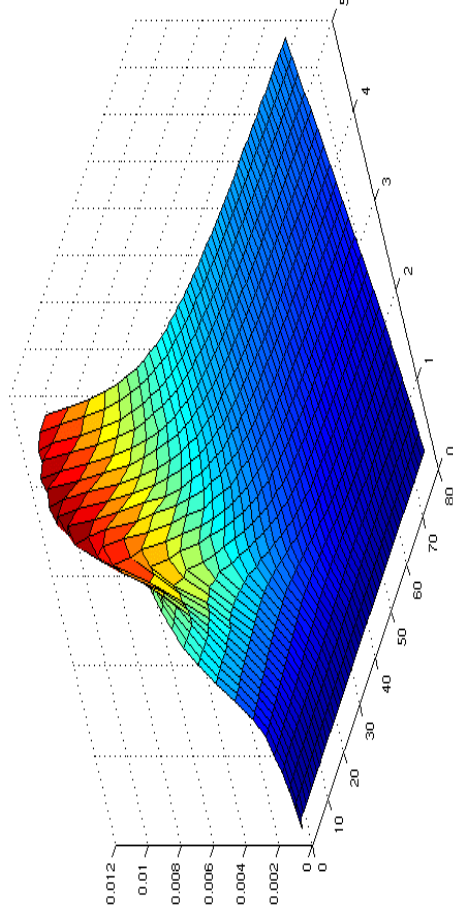


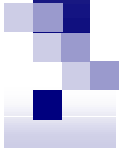
“But it doesn’t occur in X?”

- X = real problems
 - No, you just need a suitable ensemble of problems to sample from?***
- Phase transition behaviour seen in:
 - **job shop scheduling problems**
 - **TSP instances from TSPLib**
 - **exam timetables @ Edinburgh**
 - **Boolean circuit synthesis**
 - **Latin squares (alias sports scheduling)**
 - ...

“But it doesn’t occur in X?”

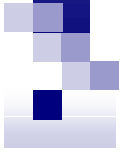
- X = some other complexity class
 - Ignoring trivial cases (like $O(1)$ algorithms)*
- Phase transition behaviour seen in:
 - polynomial problems like arc-consistency
 - PSPACE problems like QSAT and modal K
 - ...



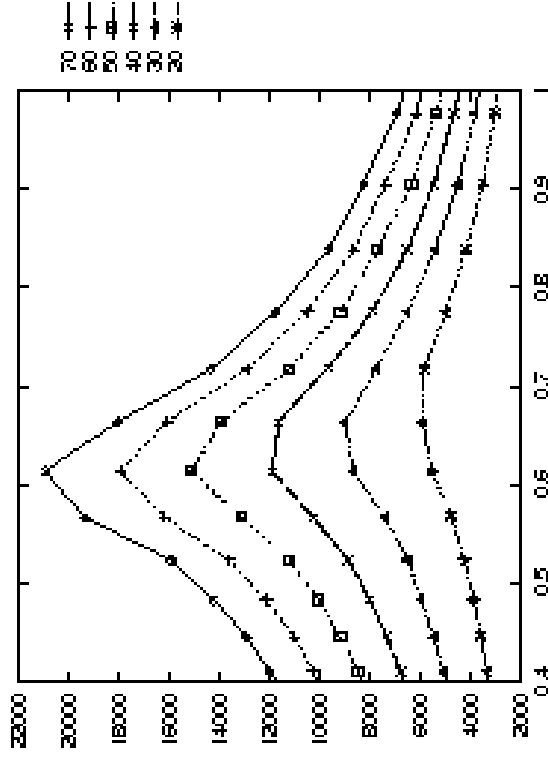


Random 2-SAT

- 2-SAT is P
 - linear time algorithm
 - Random 2-SAT displays “classic” phase transition
 - $c/n < 1$, almost surely SAT
 - $c/n > 1$, almost surely UNSAT
 - complexity peaks around $c/n=1$
- $x1 \vee x2, -x2 \vee x3, -x1 \vee x3,$
....



Phase transitions in P



- 2-SAT

- $c/n=1$

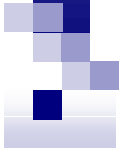
- Horn SAT

- transition not "sharp"

- Arc-consistency

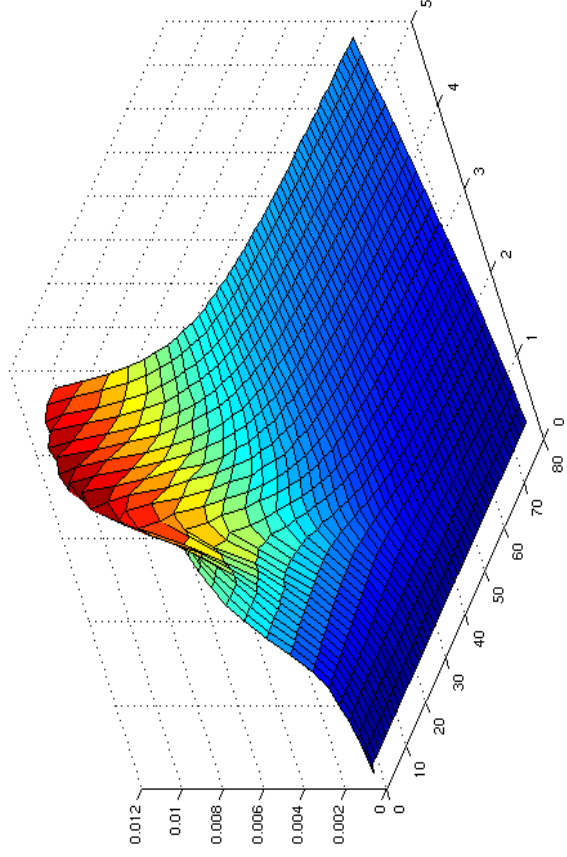
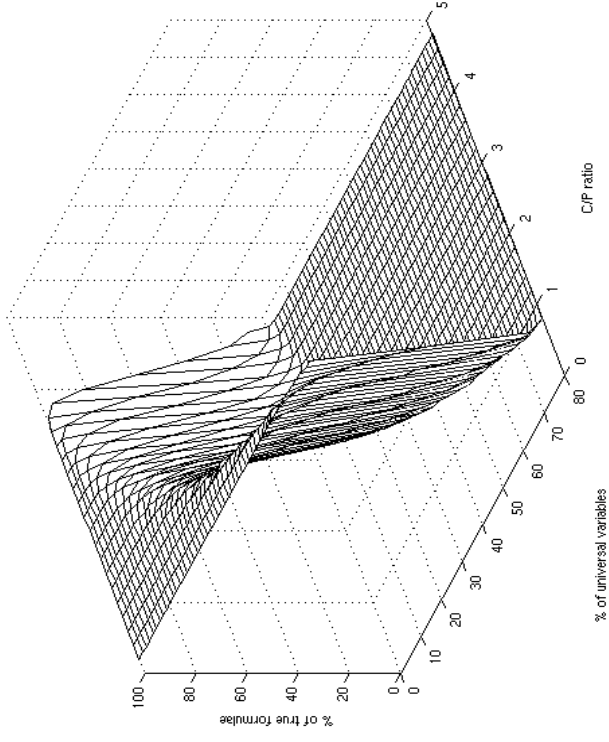
- rapid transition in whether problem can be made AC

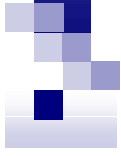
- peak in (median) checks



Phase transitions above NP

- PSpace
- QSAT (SAT of QBF)
 $\forall x1 \exists x2 \forall x3 . x1 \vee x2 \ \& \ -x1 \vee x3$





Phase transitions above NP

- PSpace-complete
 - QSAT (SAT of QBF)
 - stochastic SAT
 - modal SAT
 - PP-complete
 - polynomial-time probabilistic Turing machines
 - counting problems
 - #SAT ($>= 2^{n/2}$)
- [Bailey, Dalmau, Kolaitis IJCAI-2001]*

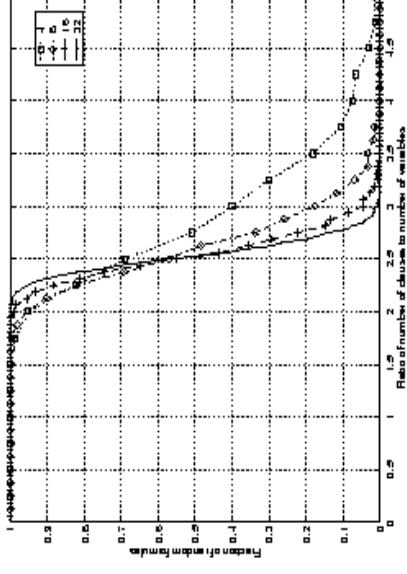


Figure 1: Phase Transition Graphs

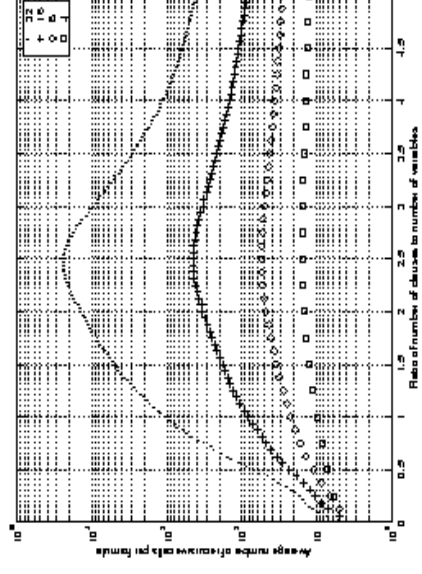


Figure 2: Performance Graphs



Exact phase boundaries in NP

- Random 3-SAT is only known within bounds

- $3.26 < c/n < 4.506$

Are there any NP phase boundaries known exactly?

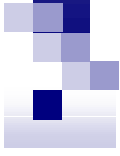
- Recent result gives an exact NP phase boundary

- **1-in-k SAT at $c/n = 2/k(k-1)$**
 - **2nd order transition (like 2-SAT and unlike 3-SAT)**

1st order transitions not a characteristic of NP as has been conjectured

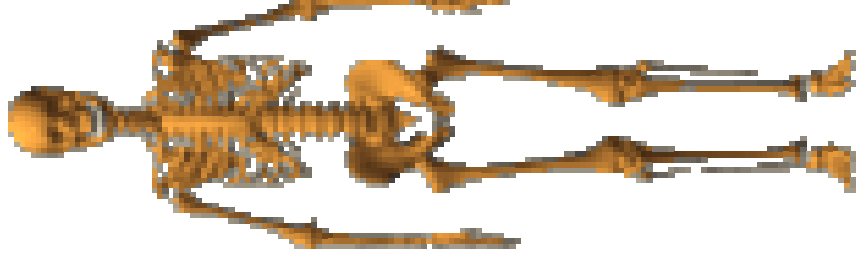
Structure

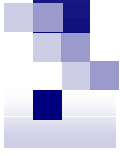
What structures makes problems hard?
How does such structure affect phase transition behaviour?



Backbone

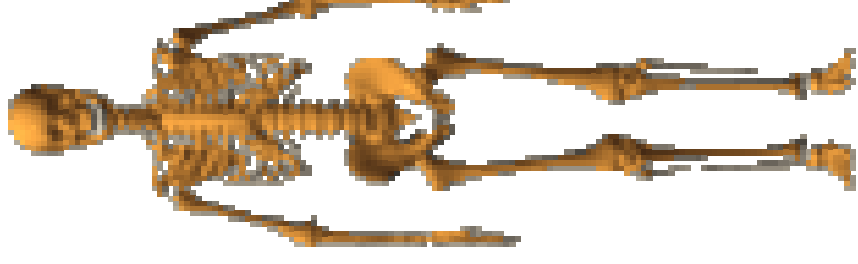
- Variables which take fixed values in all solutions
 - **alias unit prime implicates**





Backbone

- Variables which take fixed values in all solutions
 - **alias unit prime implicates**
 - Let f_k be fraction of variables in backbone
 - **in random 3-SAT**
 - $c/n < 4.3$, f_k vanishing (otherwise adding clause could make problem unsat)
 - $c/n > 4.3$, $f_k > 0$
- discontinuity at phase boundary (1st order)!***

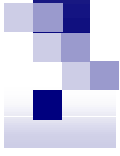




Backbone

- Search cost correlated with backbone size
 - **if f_k non-zero, then can easily assign variable “wrong” value**
 - **such mistakes costly if at top of search tree**
- One source of “thrashing” behaviour
 - **can tackle with randomization and rapid restarts**

Can we adapt algorithms to offer more robust performance guarantees?

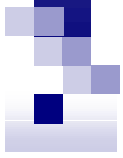


Backbone

- Backbones observed in structured problems
 - **quasigroup completion problems (QCP)**
colouring partial Latin squares
- Backbones also observed in optimization and approximation problems
 - **coloring, TSP, blocks world planning ...**

see [Staney, Walsh IJCAI-2001]

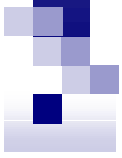
Can we adapt algorithms to identify and exploit the backbone structure of a problem?



2+p-SAT

- Morph between 2-SAT and 3-SAT
 - fraction p of 3-clauses
 - fraction $(1-p)$ of 2-clauses

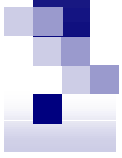




2+p-SAT

- Morph between 2-SAT and 3-SAT
 - fraction p of 3-clauses
 - fraction $(1-p)$ of 2-clauses
- 2-SAT is polynomial (linear)
 - phase boundary at $c/n = 1$
 - but no backbone discontinuity here!

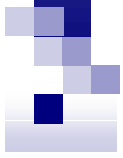




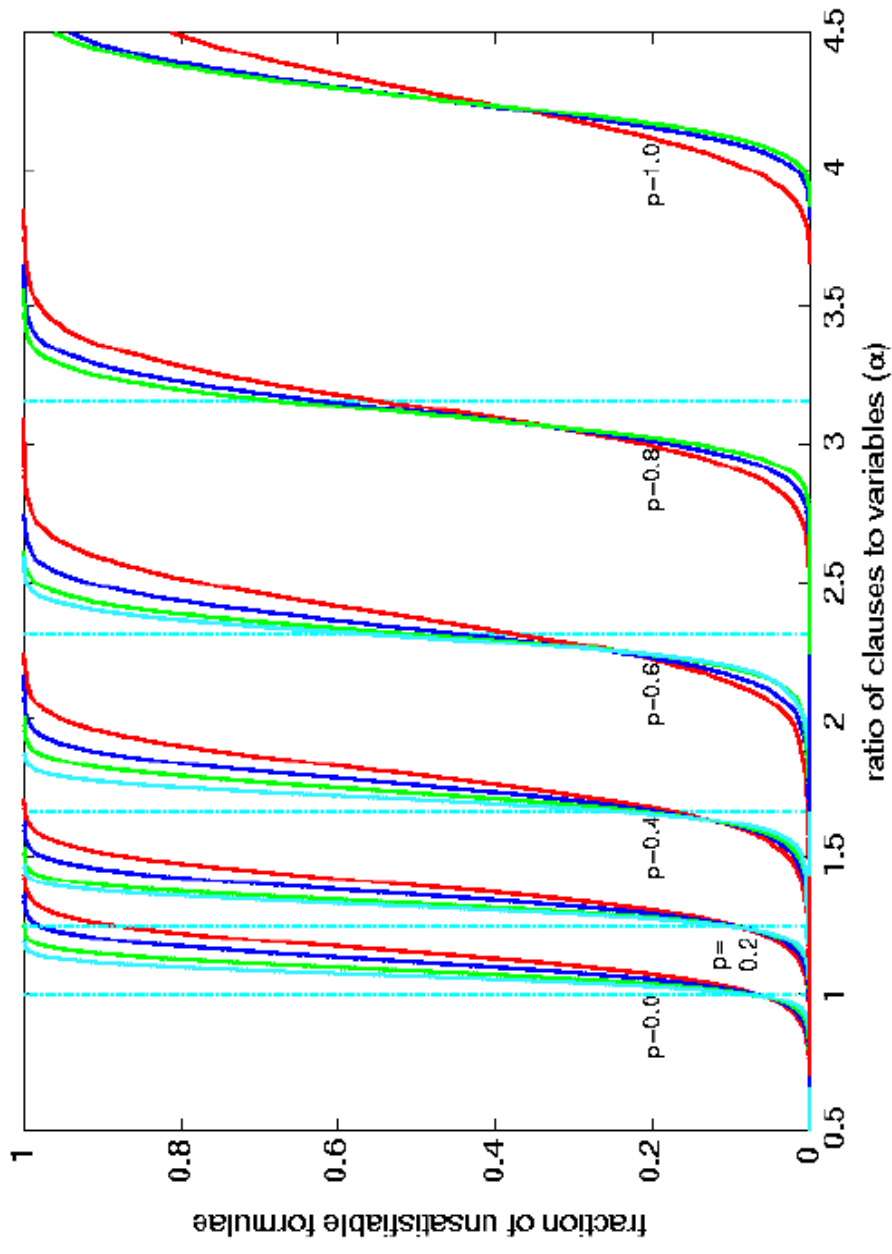
2+p-SAT

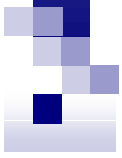


- Morph between 2-SAT and 3-SAT
 - fraction p of 3-clauses
 - fraction $(1-p)$ of 2-clauses
- 2-SAT is polynomial (linear)
 - phase boundary at $c/n = 1$
 - but no backbone discontinuity here!
- 2+p-SAT maps from P to NP
 - $p > 0$, 2+p-SAT is NP-complete

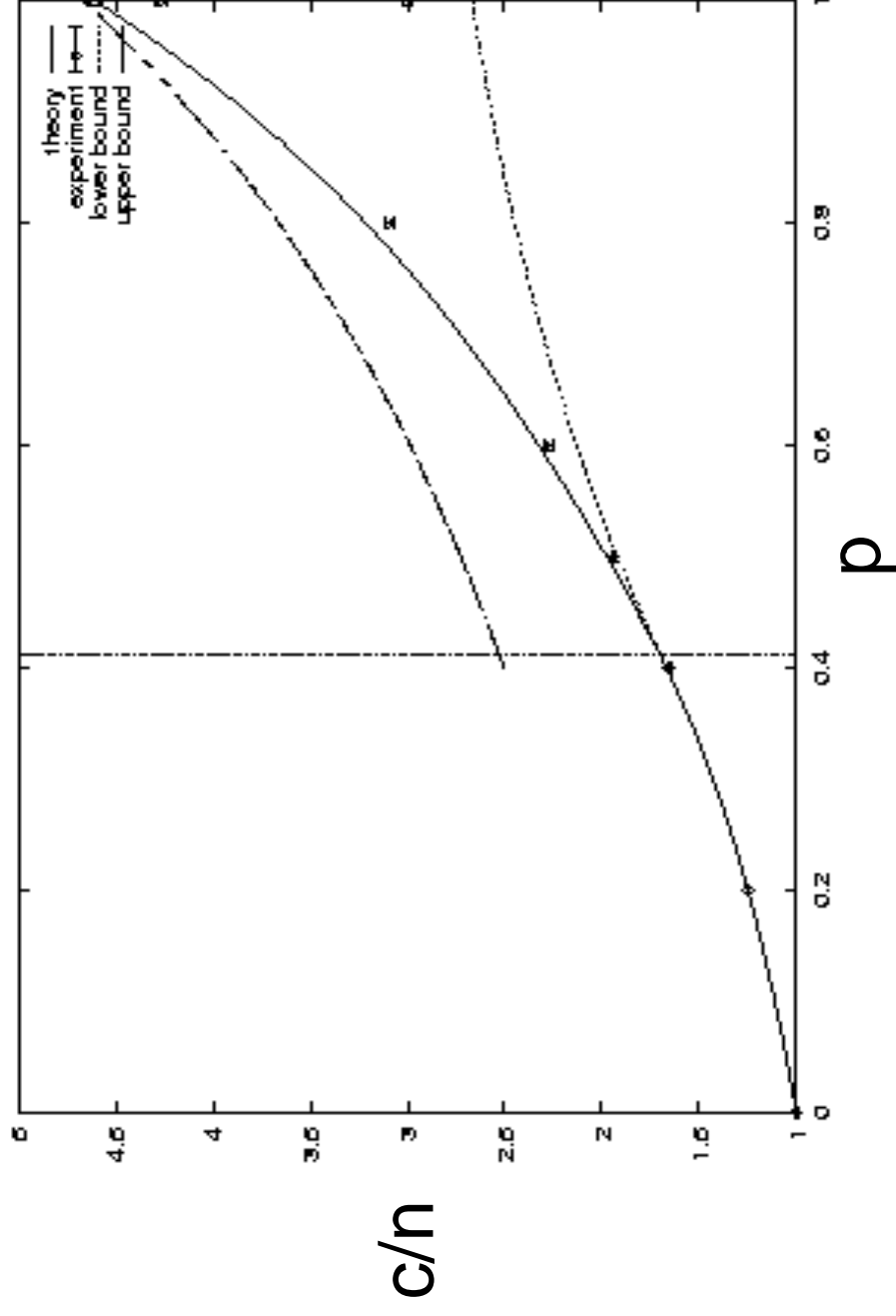


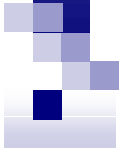
2+p-SAT phase transition





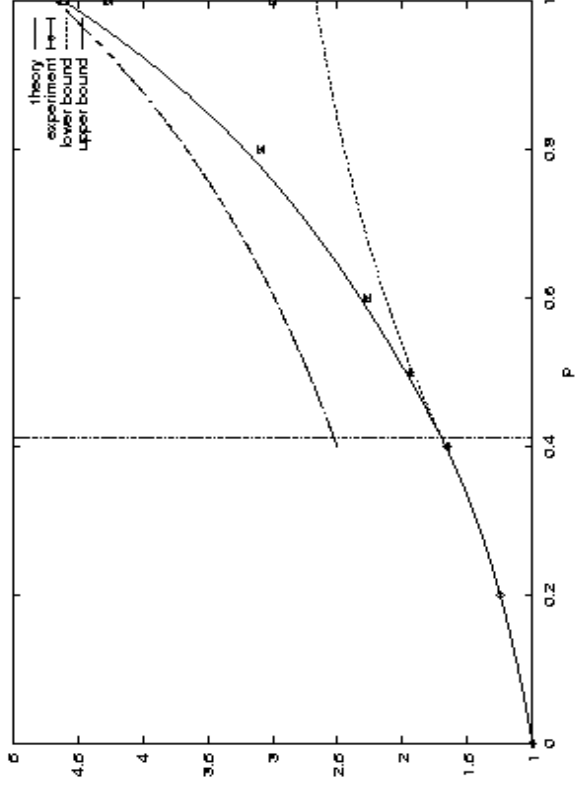
2+p-SAT phase transition

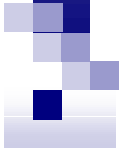




2+p-SAT phase transition

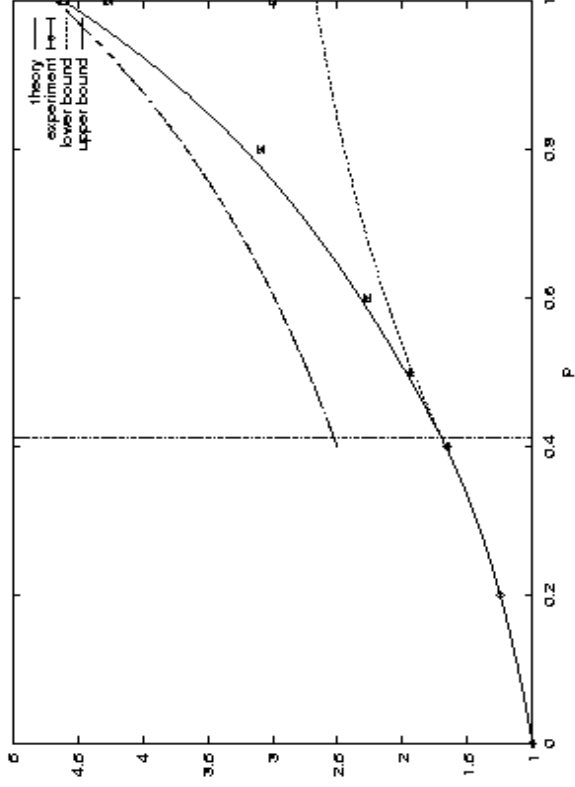
- Lower bound
 - are the 2-clauses (on their own) UNSAT?
 - n.b. 2-clauses are much more constraining than 3-clauses





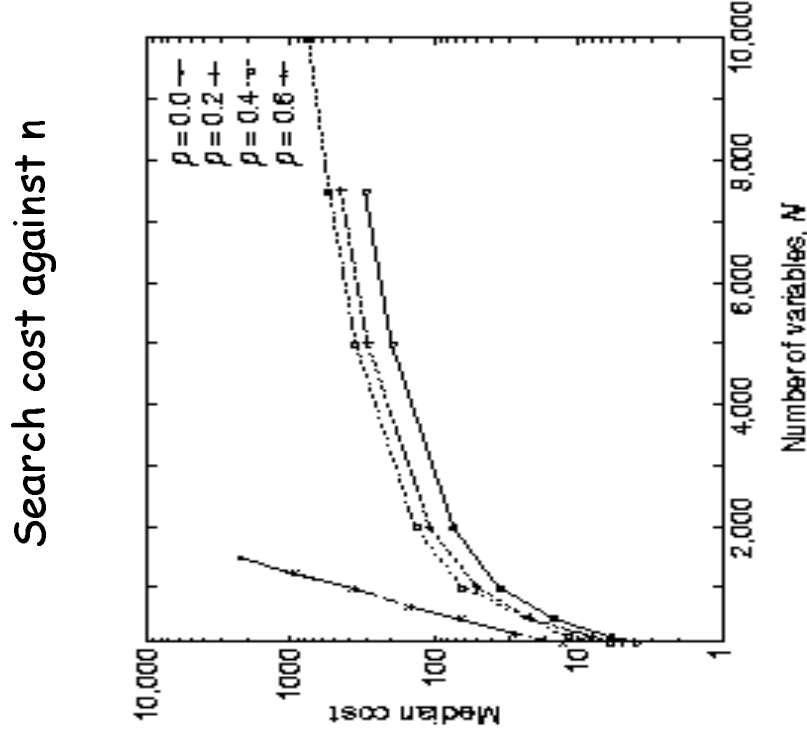
2+p-SAT phase transition

- Lower bound
 - are the 2-clauses (on their own) UNSAT?
 - n.b. 2-clauses are much more constraining than 3-clauses
- $p \leq 0.4$
 - transition occurs at lower bound
 - 3-clauses are not contributing!



2+p-SAT backbone

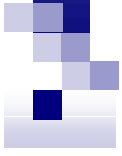
- f_k becomes discontinuous for $p > 0.4$
 - **but NP-complete for $p > 0$!**
- search cost shifts from linear to exponential at $p = 0.4$
- similar behavior seen with local search algorithms



Structure

How do we model structural features found in real problems?

How does such structure affect phase transition behaviour?

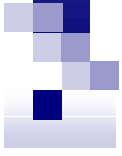


The real world isn't random?

- Very true!
Can we identify structural features common in real world problems?

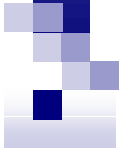
- Consider graphs met in real world situations
 - **social networks**
 - **electricity grids**
 - **neural networks**
 - ...





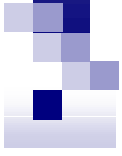
Real versus Random

- Real graphs tend to be sparse
 - **dense random graphs contains lots of (rare?) structure**



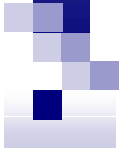
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Real versus Random

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- Real graphs tend to have short path lengths
 - **as do random graphs**
- Real graphs tend to be clustered
 - **unlike sparse random graphs**



Real versus Random

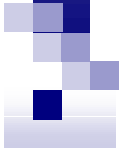
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- Real graphs tend to be clustered
 - **unlike sparse random graphs**

L, average path length

C, clustering coefficient

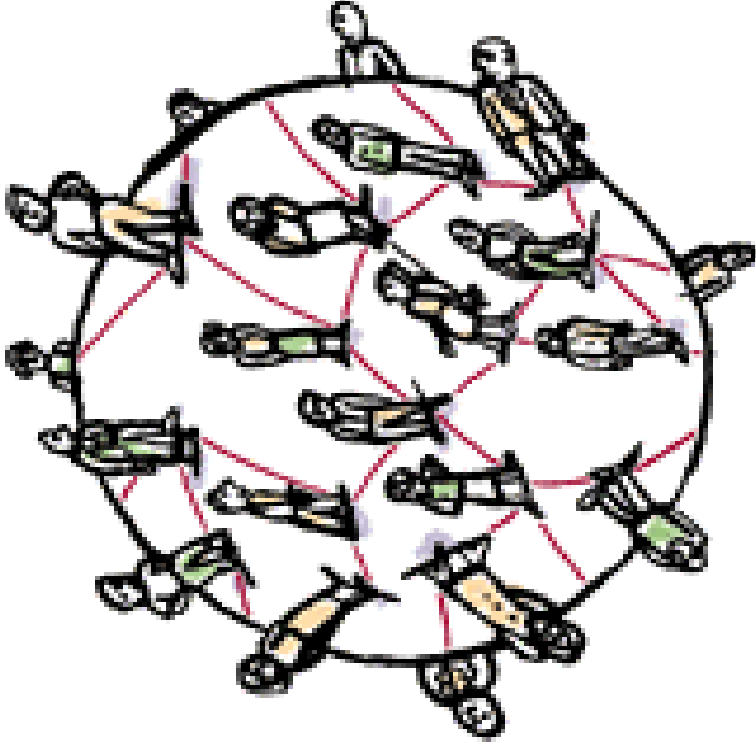
(fraction of neighbours connected to each other, cliqueness measure)

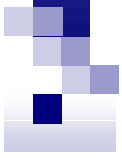
μ , proximity ratio is C/L normalized by that of random graph of same size and density



Small world graphs

- Sparse, clustered, short path lengths
- Six degrees of separation
 - **Stanley Milgram's famous 1967 postal experiment**
 - **recently revived by Watts & Strogatz**
 - **shown applies to:**
 - actors database
 - US electricity grid
 - neural net of a worm
 - ...

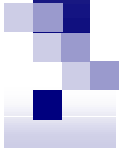




An example

- 1994 exam timetable at Edinburgh University
 - **59 nodes, 594 edges so relatively sparse**
 - **but contains 10-clique**
- less than 10^{-10} chance in a random graph
 - **assuming same size and density**

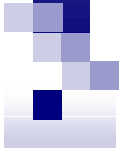




An example

- 1994 exam timetable at Edinburgh University
 - **59 nodes, 594 edges so relatively sparse**
 - **but contains 10-clique**
- less than 10^{-10} chance in a random graph
 - **assuming same size and density**
- clique totally dominated cost to solve problem





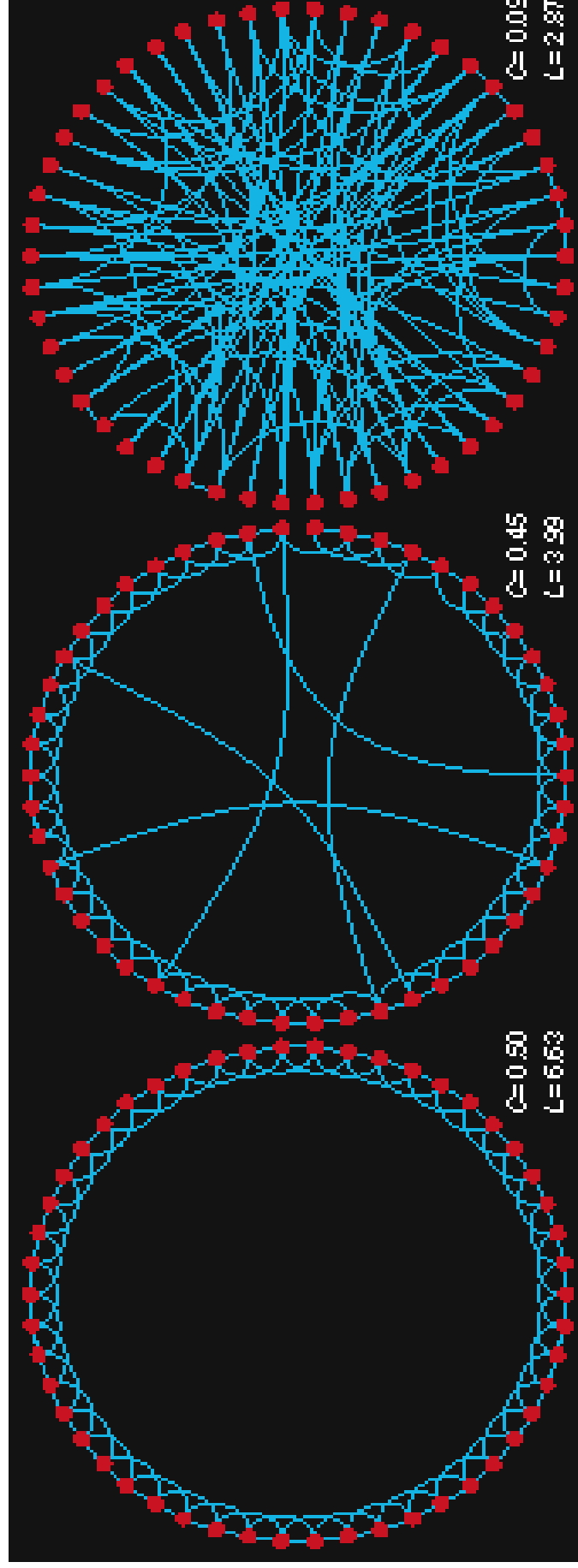
Small world graphs

- To construct an ensemble of small world graphs
 - morph between regular graph (like ring lattice) and random graph
 - prob p include edge from ring lattice, $1-p$ from random graph

real problems often contain similar structure and stochastic components?



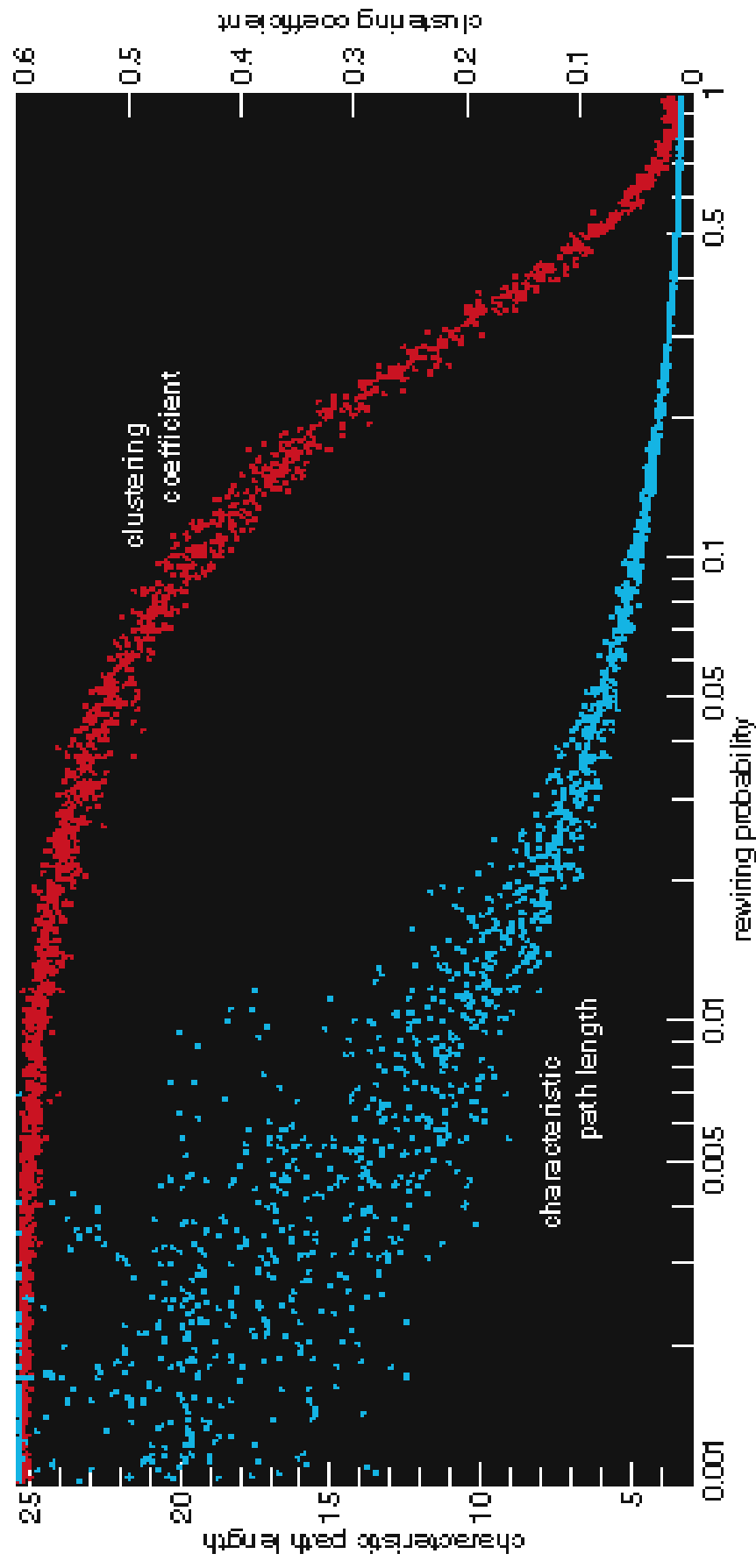
Small world graphs

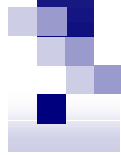


- ring lattice is clustered but has long paths
- random edges provide shortcuts without destroying clustering



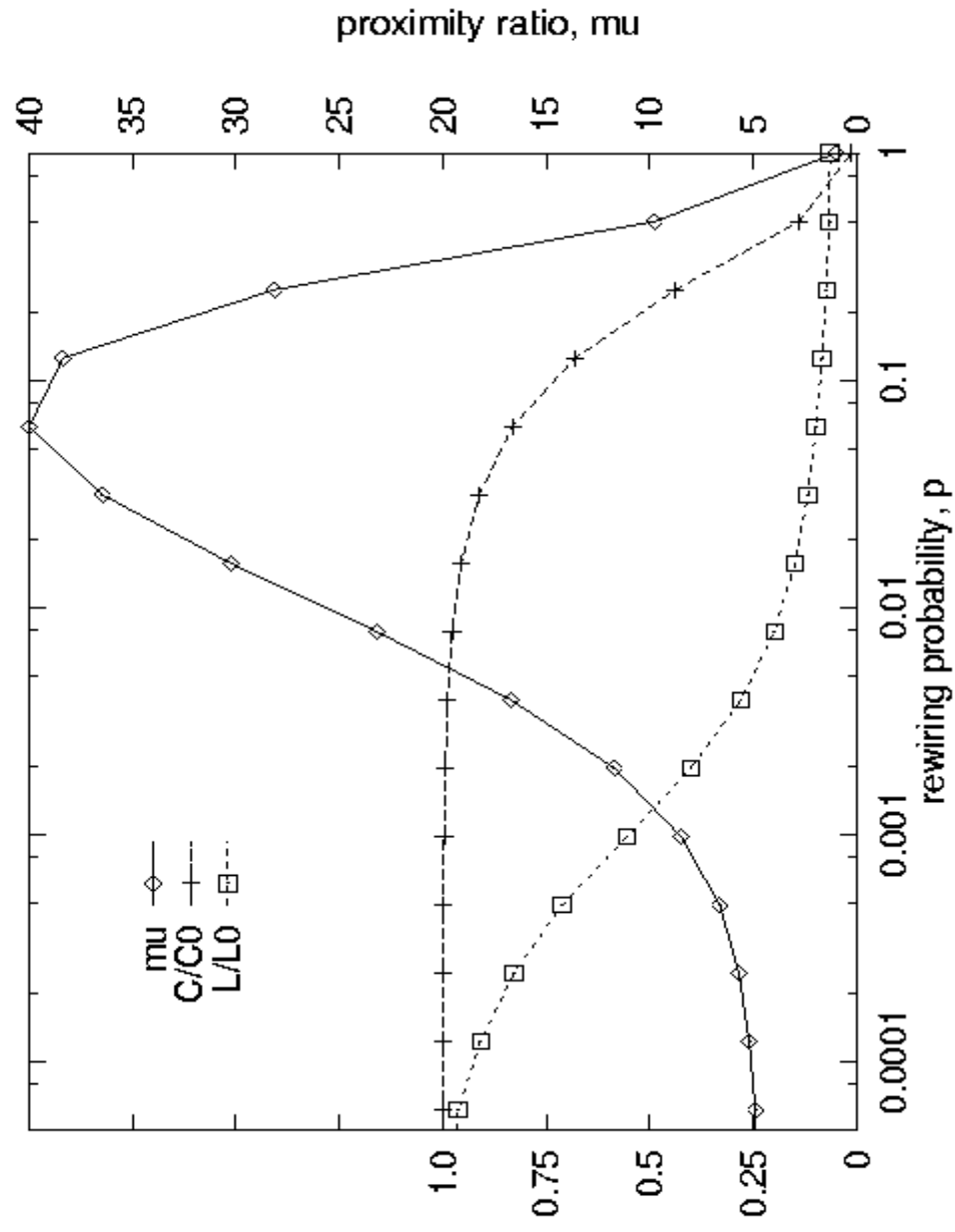
Small world graphs

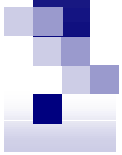




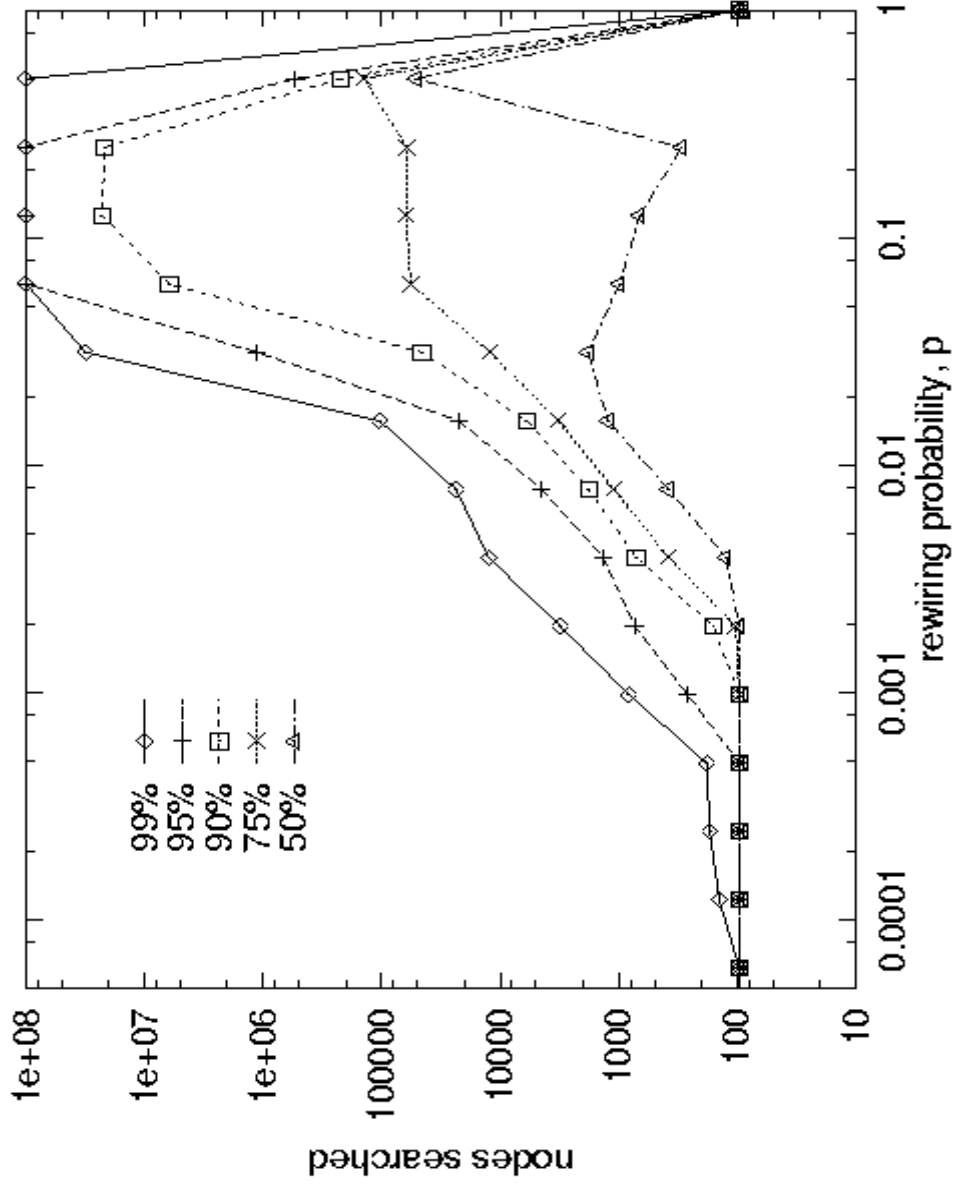
Small world graphs

normalized clustering coefficient and characteristic path length





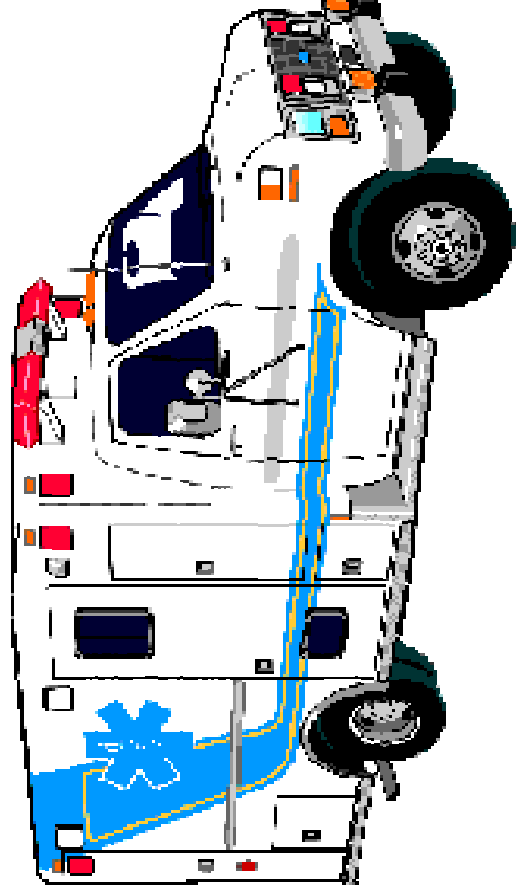
Colouring small world graphs





Small world graphs

- Other bad news
 - **disease spreads more rapidly in a small world**
- Good news
 - **cooperation breaks out quicker in iterated Prisoner's dilemma**





Other structural features

It's not just small world graphs that have been studied

- Large degree graphs
 - **Barbasi et al's power-law model [Walsh, IJCAI 2001]**
- Ultrametric graphs
 - **Hogg's tree based model**
- Numbers following Benford's Law
 - **1 is much more common than 9 as a leading digit!**
 - $\text{prob}(\text{leading digit}=i) = \log(1+1/i)$
 - **such clustering, makes number partitioning much easier**

The future?

What open questions remain?

Where to next?



Open questions

- Prove random 3-SAT occurs at $l/n = 4.3$
 - random 2-SAT proved to be at $l/n = 1$
 - random 3-SAT transition proved to be in range $3.26 < l/n < 4.506$
 - random 3-SAT phase transition proved to be “sharp”



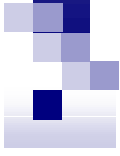
Open questions

- Impact of structure on phase transition behaviour
 - **some initial work on quasigroups (alias Latin squares/sports tournaments)**
 - **morphing useful tool (e.g. small worlds, 2-d to 3-d TSP, ...)**
- Optimization *v* decision
 - **some initial work by Slaney & Thiebaux**
 - **economics often pushes optimization problems naturally towards feasible/infeasible phase boundary**



Open questions

- Does phase transition behaviour give help answer $P=NP$?
 - **it certainly identifies hard problems!**
 - **problems like 2+p-SAT and ideas like backbone also show promise**
- Problems away from phase boundary can be hard
 - **over-constrained 3-SAT region has exponential resolution proofs**
 - **under-constrained 3-SAT region can throw up occasional hard problems (early mistakes?)**

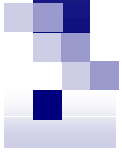


Research directions in SAT

- Algorithm development
 - **Fast but cheap solvers (chaff from Princeton)**
 - Basic operations are constant time (e.g. branching heuristic, finding unit clauses, ..)
 - **Nogood learning**
 - **Randomization and restarts**
 - Learning across restarts
- Domain enlargement
 - **New encodings into SAT**
 - **Beyond the propositional (QBF, modal SAT, ...)**

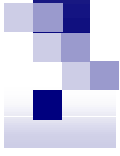
Summary

That's nearly all from me!



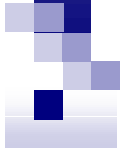
Conclusions

- Phase transition behaviour ubiquitous
 - **decision/optimization/...**
 - **NP/PSpace/P/...**
 - **random/real**
- Phase transition behaviour gives insight into problem hardness
 - **suggests new branching heuristics**
 - **ideas like the backbone help understand branching mistakes**



Conclusions

- Propositional satisfiability (SAT)
 - **Very active research area**
 - SAT2002
 - **Useful for understanding source of problem hardness**
 - **Useful also for solving problems**
 - E.g. Planning as SAT, model checking via SAT, ...
 - **Developing new algorithms**
 - E.g. Randomization and restarts, learning, non-chronological backtracking, ..



Very partial bibliography

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See <http://www.cs.york.ac.uk/~tw/Links/> for more